Chapter 2

Real Market Securities

So far, we have kept everything at a rather abstract level, remaining comfortably in the realm of theoretical economics. Let's look quickly at the real-world assets this theory is supposed to describe.

2.1 The basic assets

2.1.1 Stocks

A share of stock represents ownership of a piece of a corporation, called equity. Its value comes fundamentally from the real economic worth of the underlying operation over its whole future lifetime. Since this is very difficult to determine with any accuracy, the stock price is rather determined by what other people are willing to pay for it. This price fluctuates as popular opinion changes, and as news is revealed about the company and the environment.

The "efficient-market hypothesis" says that all information that anyone has about the value of the stock is reflected in the instantaneous stock price (for a popular account, see Malkiel). That is, if everyone believes the price will go up later, they will start buying now and it will go up now. The main reason the price changes in the future is because of the random arrival of new information. Thus a random-walk model is the most logical for the motion of stock prices.

Note, however, that the fact that the changes in price themselves are unpredictable does not necessarily mean that their statistical properties are completely unpredictable. We may not be able to tell whether a stock will go up or down in the next half-hour (if we could do that consistently,
we could become very rich very quickly), but we may be able to guess, based on observation of past history, what the *approximate size of motion* we expect over a half-hour, over a day, or over a few months. It is this consistency that our mathematical techniques are based on. Thus, in our binomial tree models, we assumed we could decided in advance what the *set* of possible paths was, though we had no idea and no opinion about which one would actually be chosen.

Of course, statistical consistency is possible only when no one is in a position to influence the statistic being measured. It is now possible to buy contracts on volatility itself, and it is possible that the existence and active trading of these products may change the behavior of the volatility used to model options.

### 2.1.2 Bonds and interest rates

A *bond* is a commitment to pay back a fixed amount of money at a fixed future date. Assuming the party making the commitment is reliable, the present value of this commitment depends on the interest rate assumed to hold between now and the payment date. If interest rates rise, then bond prices fall.

In the last section, we assumed the existence of a single interest rate $r$, constant in time, at which we could borrow or lend money. But as anyone who has a credit card, a mortgage, a money market account, and a savings account knows, there is a wide variety of interest rates in the market.

Furthermore, interest rates change, in response to Alan Greenspan’s intervention or to market forces as with stocks. (My mortgage rate jumped up a quarter-point when Pat Buchanan won the 1996 New Hampshire Republican primary.)

In the context of pricing options on stocks, our answers to both these questions are influenced by the fact that stock motions are much more volatile than interest rate motions, so the time scales of interest in option pricing are short compared to the times characterizing interest rate changes.

The interest rate that is usually used for the $r$ in our formulas is a short-term rate, called the *overnight* rate, at which large institutions with impeccable credit can lend to each other. Because of the disparity of time scales, the value of $r$ generally does not have a very large influence on the computed option value.
The dynamics of long-term interest rates, and the pricing of derivatives on them, are an extremely interesting and mathematically challenging area, which we will hear a little more about later in the course.

Another active area of much current research is the determination of spreads on corporate bonds, that is, the additional interest required to convince someone to lend to a company that has a nonnegligible risk of going bankrupt and being unable to repay.

2.1.3 Foreign exchange

All sorts of national currencies fluctuate against each other in response, as with stocks, to investors’ assessment of the relative desirability of holding money in one country or another. Derivative contracts on foreign exchange can be priced using similar techniques as for derivatives on stocks. One difference is that account must be taken of the interest that can be earned by holding the foreign currency in comparison to the domestic.

2.2 Derivatives

Almost any contract that human imagination can invent is probably being bought and sold somewhere on the planet at this very moment. Let us focus our attention right now on the simplest, most important, and most widely traded derivative contracts.

2.2.1 Forwards and futures

A forward contract is an agreement to buy a specific asset for a specified price, the strike price or delivery price, on a specified future expiration date. There is no optionality on either side: both parties are obligated to exchange cash and the asset when that date arrives, unless they sell the contract to someone else before then. A futures contract is a highly standardized version of a forward contract that can be traded on an exchange.

The value of the forward contract at expiry is just the difference between the price of the underlying asset at that time and the strike price. We write this as

\[ F_T = S_T - K \]
Figure 2.1: The payo function at expiration time of a futures or forward contract with strike $K$, as a function of the asset price at that time. On the left, the payo to the person who is long the contract. On the right, the payo to the person who is short, obviously the negative of the long position (since money is exchanged only between these two parties).

where $F_T$ is the value of the contract at time $T$, and $S_T$ is the market price of the underlying at $T$. Indeed, forward and futures contracts are often settled in cash rather than by actually exchanging the asset. This simple payoff function is shown in Figure 2.1. (We shall use letters $F$, $C$, $P$, etc to denote the price of specific derivatives such as forward contracts, calls, puts, etc; these correspond to the $V$ of Chapter 1.)

The real question is, what should be the current price $F_0$ of a forward contract? How much should you pay to sign up for this deal? Here we have the simplest example of risk-neutral pricing. Suppose that $S$ is the price per ounce of gold. Suppose someone offers you a forward contract to purchase one ounce of gold a time $T$ from now for a price $K$. What should you pay for this contract?

The first thing to figure out is whether the price of the contract depends on what you think the price of gold will do in the interval between now and $T$. You might think that the more likely the price is to rise, the greater the present price $F_0$ of the forward contract should be. But our discussion in Chapter 1 should have convinced you that subjective probabilities are often not important.

The real answer is found by duplicating the payoff. Suppose you sell someone a forward contract for one ounce of gold. He gives you $F_0$ cash now, where $F_0$ is to be determined. At time $T$, he will give you an
additional $K$ cash, and you will be obliged to hand over one ounce of gold. You want to guarantee that you can do this, without incurring any risk because of possible motions of gold price between now and then.

The key is to buy the gold right now, and use bonds with guaranteed interest payments to take up any slack. So go buy one ounce of gold at the current price $S_0$. Also, borrow $Ke^{-rT}$ dollars. At time $T$, your customer gives you $K$ dollars which you use to exactly pay off your loan, and you give him the gold. The initial out-of-pocket cost to you of this strategy is $S_0 - Ke^{-rT}$, and that is exactly the price you must demand from him:

$$F_0 = S_0 - Ke^{-rT}$$

If the forward contract is offered in the market at any different price than this, you can make a sure profit by running this cycle one way or the other.

In futures contracts, the delivery price is often determined so that no money changes hands now; $K = e^{rT}S_0$ so $F_0 = 0$. The value $K$ is the “future” price of the asset. Thus the futures price of an asset is simply a direct reflection of its present price, with slight modifications for interest costs.

This analysis assumes that the asset does not generate any return for the holder—a lump of gold, for example. If it is a stock that pays dividends, or a foreign currency that can be invested in the foreign country, then the above formula must be modified slightly.

### 2.2.2 Options

As its name implies, an **option** gives you, the holder, the choice whether to execute a certain transaction or not. A **call option** gives you the right to purchase a specified asset (from the **counterparty**: the person who sold you the option) for a specified price $K$, the **strike price**, at some future date or range of dates. A **put option** gives you the right to sell the asset (to the counterparty) for a specified strike price $K$. Doing the purchase or the sale is called **exercising** the option.

Options normally have an **expiration date** $T$ beyond which they cease to exist (“perpetual options” do exist). At the expiration date, the value of the option is uniquely known as a function of the stock price on that date, given by a **payout function**. For a call option, you will clearly choose to exercise it if and only if $S > K$, in which case the value is $S - K$; in that case the option is said to be **in the money**. If $S < K$ at expiration, you
would lose money by purchasing the asset at price $K$ (since you can get it cheaper in the market), and the option expires worthless; it is out of the money. A put option is exactly the converse.

We know the values $C_T$ and $P_T$ at the expiry time $t = T$ in terms of the underlying asset price $S_T$ at that time:

Call: \[ C_T = \max\{S_T - K, 0\} \]
Put: \[ P_T = \max\{K - S_T, 0\}. \]

(Figure 2.2) Since the holder of the option always the freedom to tear it up and throw it out the window, its value is never negative. The short position is exactly opposite to the long position.

Options are distinguished among themselves by two properties: First, whether you have net positive or negative exposure to motions of the stock price. If the payout function has generally positive slope, you have long or “bullish” exposure: you benefit if the price rises. The second distinguishing factor is whether the exercise decision is yours or your counterparties. If the optionality is on your side, then your payoff function has only convex corners.
As outlined above, the most important purpose of “classical” financial mathematics is to determine the “correct” present value for a security, thus $C_0$ and $P_0$ for call and put options. Because the payoff functions in Figure 2.2 are nonlinear, the reasoning is more subtle than for forward contracts. We will need to use the full mechanisms of Chapter 1, together with refinements for continuous time that we explore in Chapter 3.

Options can be used to speculate, meaning to take on additional risk in the hope of obtaining higher return. If you believe a certain stock is sure to go up, you can of course purchase the stock and hold it. But you can also purchase a call option on the stock for much less than the stock itself. Your gains are much amplified if the stock goes up. But if the stock closes the period below the strike price of the option (even if it goes up later) everything you spent for the option is lost.

Options can be used for hedging pre-existing risk. Almost all home mortgages are options on interest rates: you can refinance when you choose if rates drop, but are protected from rises in rates.

Options come in several different varieties. The most important distinction is exactly when exercise is allowed. In Chapter 1, we have been implicitly been talking about European options, which can be exercised on exactly one future date $T$, not before and not after. These can be valued in closed form, as we shall see later.

Most equity options are American options, meaning that they can be exercised at any time (of the holder’s choice) before expiration. After the expiration date, they are worthless. Typical lifetimes for options are three, six, and nine months. Addition of the possibility of early exercise makes an American option always at least as valuable as its European counterpart. Pricing American options is more difficult than pricing European options.

Ordinary calls and puts are called vanilla options to distinguish them from the myriad kinds of exotic options with more complicated formulas. For example, Bermudan options (between American and European) can be exercised only on one of a set of prescribed dates before expiration. Asian options pay a value at expiration that depends on the average value of the asset price since the starting time. Lookback options pay a value that depends on the maximum or the minimum of the asset price over some specified period.

Barrier options change their value if the asset price crosses a specified level before expiration: down-and-out and up-and-out barriers become valueless if the price reaches the threshold; down-and-in and up-and-in barriers are initially without value, but turn into standard options if the
price reaches the specified level before expiration.

Options and other derivatives are a way to trade risk between different participants in the market. Common sense—this can be backed by classical economic theory based on Pareto optimality—suggests that the more freedom people have to tailor their world, the better off they are. Indeed, when you insure your house, you are transferring risk to the insurance company. The probability and the cost of destruction do not change, but the company has a more robust risk appetite than an individual (and in fact, the insurance company then redistributes the risk even more widely).

Of course, freedom to trade risk, like freedom to do anything else, can lead to problems. Recent well-publicized disasters (Orange County, MetalGesellschaft, Long-Term Capital Management) have illustrated the difficulty people can get themselves into in their search for profit.

**Put-call parity:** Options of different types satisfy certain relationships, of which the most famous is put-call parity. Consider a European call option, a European put option, and a futures contract on the same asset,
all with the same strike $K$. It is clear by examining Figures 2.1 and 2.2 that at expiration, being long the call and short the put is equivalent to being long the forward, so

$$ C - P = F. $$

Therefore, these two portfolios must have the same value at earlier times as well. Substituting the value of the forward contract, we have

$$ C = P + S - Ke^{-rT} $$

a time $T$ before expiration. This formula is useful when the value of either a call or a put has been determined and the other one is desired.

**A real example:** Figure 2.3 shows some actual call and put option values (from the online *Wall Street Journal*). Note that the $x$-axis in this picture is the *strike* price, not the *stock* price as in the other pictures (current stock price in this example is $S_0 = 7713/16 = 77.8$). Thus the call option prices slope downwards: the less you want to be able to buy the asset for, the more you have to pay for the option.

The solid lines in the graph are the payoff function: $\max\{S - K, 0\}$ for the call and $\max\{K - S, 0\}$ for the put. Note that, as advertised, the prices of the options that are near expiration lie very close to these lines. An option with expiration in a specified month may be exercised until the *end* of that month, so the January options have about three weeks left.
Chapter 3

The Black-Scholes Equation

Hopefully these practical details will have whetted your appetite to return to the basic principles of no-arbitrage pricing, and to determine how to find fair values for complicated objects such as options at times before their expiration. To do this, we need to return to our tree, and figure out how to take it to a continuum limit.

3.1 Refining the tree

In Section 1.2, we constructed a tree having $N$ time steps. In the formulation there, $N$ could be any number. For the given $N$, we were free to choose the $\frac{1}{2} (N + 1)(N + 2)$ stock values $S_{ij}$ that define the geometry of the tree (we restrict ourselves to recombining trees). As long as $S_{00} = S_0$, the current stock price, we will come out with a value for the current option price, which hopefully will match what we read in the newspaper.

Now, if the resulting value is to mean anything, it should not depend on the detailed properties of the tree, which is after all our own invention. At least, it should depend only on certain well-behaved properties of the tree, which we can correlate with properties of the stock we can observe in the real world.

Our overall strategy is the following: We are going to take $N \to \infty$, which means that our tree will be very closely sampled in time. As we do so, the number of nodes in each level will also go to $\infty$, and we will make sure that as they do, they sample price space more and more finely. That is, the nodes will be closely spaced in both directions, and it is reasonable to hope that in the limit, the node values $V_{ij}$ will converge to a smooth function $V(S, t)$. 

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This function will have terminal values \( V(S, T) = \Lambda(S) \), the payoff function. The relationships between the values \( V_{ij} \) at neighboring nodes on the tree will approach a *partial differential equation* (PDE) relating local derivatives of \( V(S, t) \). Then we will solve the equation to obtain the single value of interest \( V(S_0, 0) \), the current option price. Note that to obtain a picture such as Figure 2.3, we will have to repeat this procedure for each data point, each time taking a different payoff function (calls and puts with different strikes). This PDE will be the celebrated Black-Scholes equation, for which they got the Nobel prize.

In order to take the limit \( N \to \infty \), we need to specify a regular structure for our tree (it would make no sense to construct it differently for each \( N \)). We need to specify a rule for determining the children \( S_{i+1,j} \) and \( S_{i+1,j+1} \) in terms of each parent node \( S_{ij} \). We shall do this by specifying the up and down ratios \( u \) and \( d \), rather than the differences:

\[
S_{i+1,j} = dS_{ij}, \quad S_{i+1,j+1} = uS_{ij}.
\]

The ratios \( u \) and \( d \) will be the same everywhere on the tree. In our model, therefore, in each time step the stock price can either gain a fixed percentage or lose a fixed percentage. Figure 3.1 shows a tree with constant ratios.

You may believe that this is more plausible than fixed increments.
example, if the initial price is $S_0 = \$100$, we might believe a reasonable motion is $\pm $5 in one time interval. If this stock should hit a succession of “unlucky” moves, so that its price drops to $\$20$, then the $\$5$ intervals will start to look very large; we may prefer to believe that in that case the motions will become smaller in proportion.

It’s not very convincing to argue that one model is more plausible than another, since none of it yet appears very plausible at all. Perhaps a more convincing reason is that if we use constant increments, then for certain combinations of the initial price, the increment, and the number of steps, some of the prices on the leaves may become negative. Since a real stock price never becomes negative (even if the company goes bankrupt with lots of debt, the shareholders can just rip up their sharess), we will not know how to evaluate our derivative value in that event.

We do this in the following way. First, let us require that the time levels be equally spaced, with spacing $k = T/N$. Next, we pick a “spread” $h$, and a “centering term” $s$, and we define the up and down ratios to be

$$ u = \exp\left[s k + \frac{1}{2} h\right] \quad d = \exp\left[s k - \frac{1}{2} h\right]. $$

The reason for this choice is as follows:

- The ratio of the stock price at two successive nodes is

$$ \frac{u}{d} = e^h, $$

so $(u - d)/d \approx h$, and $h$ deserves to be called the spread.

- The geometric mean of the stock price at two successive nodes is

$$ \sqrt{ud} = e^{sk}, $$

so the tree is “drifting” upwards at a fractional rate $s$ per unit time.

Note that each of these parameters is independent of the other. Both of them may depend on $N$ and hence $k$.

Now, $s$ has an action very similar to that of the interest rate $r$. Since the interest rate played an important role in our pricing formula, we might expect that the relationship between $s$ and $r$ will be important in this model.

Indeed, we must respect the inequality constraint that gives a positive pricing measure; here that requires

$$ -\frac{1}{2} h < (r - s)k < \frac{1}{2} h. $$
But, as long as this constraint is satisfied, \( s \) will not make any difference at all. We shall find that in the limit \( N \to \infty \), the option price determined on the tree is controlled entirely by \( h \).

Now let us return to our pricing formulas of Section 1.1.6. Applying (1.1) on our tree, with constant ratios \( S_+/S_0 = u \) and \( S_-/S_0 = d \) (and \( T \to k \)), we find the pricing probability

\[
q = \frac{e^{rk} - d}{u - d} = \frac{e^{(r-s)k} - e^{-h/2}}{e^{h/2} - e^{-h/2}}
\]

the same at every node. Then we can directly apply the pricing formula (1.3),

\[
V_{i,j} = e^{-rk} \left( q V_{i+1,j+1} + (1 - q) V_{i+1,j} \right)
\]

(see Figure 3.2) one level at a time to compute \( V_{ij} \) on the whole tree. It only remains to see what happens as \( N \to \infty \), so \( k \to 0 \).

### 3.2 Continuum limit

We are almost done. In order to take the limit, we need only to specify how \( s \) and \( h \) behave as \( k \to 0 \). We shall choose \( s \) to be constant as \( k \) decreases. As for \( h \), we need it to go to zero along with \( k \), so that our mesh yields nearly continuous price motions.

We shall choose \( h \) to vary so that

\[
k = \lambda h^2, \quad \lambda \text{ constant as } h \to 0.
\]

(If you prefer, you can think of this as \( h = \sqrt{k/\lambda} \).) It is not clear that this will be the right scaling. But if we do the computation with this scaling, we can explore other scalings by considering \( \lambda \) to be very large or very small. (For example, if you thought we should take \( k = ch \), then I would argue that that is equivalent to setting \( \lambda = ch \), so we can do the computation my way and then see what happens if \( \lambda \) is very small.)

Once we choose \( s \) and \( \lambda \), our entire tree is therefore described by the single parameter \( k \). We can take the limit \( k \to 0 \) and see what happens. The result can be derived rigorously using methods of finite-difference analysis. This theory says that, under assumptions we have made above (principally, that \( 0 < q < 1 \) so that the method is stable),
The node values $V_{ij}$ approach a smooth function $V(S, t)$ that solves a partial differential equation. This PDE can be determined by replacing the node values by the limit function evaluated at the node points. The discrete relationship between node values will then no longer be exactly satisfied. Expanding everything in a local asymptotic series, and requiring that the leading-order term vanish, gives the PDE.

In this case, we examine one leaf of the tree, that has the structure shown in Figure 3.2. The vertical lengths of the segments are

$$h_+ = (u - 1)S$$
$$h_- = (1 - d)S,$$

where $S = S_{i,j}$, the vertical coordinate of point $O$.

Following the prescription of finite-difference analysis, we suppose that the node values are given by samples of a smooth function, and we make the local asymptotic expansions

$$V_{i,j} = V - kv_t + \frac{1}{2}k^2V_{tt} + \cdots$$
$$V_{i+1,j} = V - h_- VS + \frac{1}{2}h_-^2V_{SS} + \cdots$$
$$V_{i+1,j+1} = V + h_+ VS + \frac{1}{2}h_+^2V_{SS} + \cdots$$
where values of $V$ and derivatives that do not carry labels are evaluated at point $O$.

Now all we have to do is plug these expansions into (3.1), expand everything in powers of $h$, and see what the leading term in the error is. We shall spare you the details (the easiest is to toss everything into Mathematica) and just give the final result:

$$V_t + \frac{1}{8\lambda} S^2 V_{SS} + r SV_S - r V = 0.$$ 

Of course, as $h \to 0$, the values $V_{N,j}$ tend smoothly to the values $V(S, T)$, at expiration where the value is unambiguously known. This equation is \textit{backwards parabolic} except possibly for some awkwardness near $S = 0$, so we have a completely defined problem for the option value: we solve the PDE and extract the value $V(S_0, 0)$.

Note that $s$ has disappeared from the limiting PDE. What happens is that $q$ adjusts to exactly compensate for the drift term $s$. This fact is the reflection of what we have seen several times so far: if a price for a derivative can be obtained by arbitrage arguments, then it is of no significance what you believe the asset will do.

The limiting procedure we have employed is a little opaque for two reasons: first, because we have invoked results from finite difference analysis, and second, because we have skimmed over all the algebra. A simpler example may make the result clearer.

The pricing formula (3.1) essentially says that each node value $V_{i,j}$ is a sort of average of the two node values to its right. Of course $q$ is not exactly $\frac{1}{2}$, and there is the discount term $e^{-rk}$, but essentially it is an average. So suppose that $r = 0$ and $q = \frac{1}{2}$, and let us suppose that we set $s = 0$. In such a case it is not too hard to convince yourself that the result of this repeated averaging converges to a solution of the diffusion equation when the grid is refined. That’s the essence of this result.

Now we can return to a question we raised earlier: how did we know the scaling should be $k \sim \lambda h^2$? We can answer this question by using our knowledge of the diffusion equation:

1. If $\lambda$ were extremely small, then the diffusion coefficient would be very large. The solutions would quickly reduce to constants. But option prices are demonstrably not constant functions.

2. If $\lambda$ were extremely large, then the diffusion coefficient would be extremely small. The PDE would be very close to a pure convective
equation, and its solutions would be translated and scaled copies of the terminal data. But option prices at times before expiry have a different shape than the payoff function; they are smoothed, as if by the action of a diffusive term.

Let us define a new parameter $\sigma$, the volatility, by
\[
\frac{1}{8\Lambda} = \frac{1}{2} \sigma^2.
\]
In other words, we specify that for a given $k$, our up and down steps should be chosen so that
\[
h = 2\sigma\sqrt{k}.
\]
Then we can write the Black-Scholes equation in its standard form:
\[
-V_t = \frac{1}{2} \sigma^2 V_{SS} + rSV_S - rV \quad \text{in } t < T.
\] (3.2)

with
\[
V(S, T) = \Lambda(S).
\]
We have put the negative sign on $V_t$ because this equation is backwards parabolic: it is well-posed when final data, rather than initial, is given.

Let’s pause to think about what we have just derived. We have restricted our attention to European-style derivatives (no early exercise) with a finite upper time horizon at which the value is unambiguously known. For that type of problem, our assertion is that the value of any derivative security may be represented as a smooth function $V(S, t)$ of time and of possible future asset prices $S$, satisfying the same universal equation. Valuing a derivative then becomes a practical problem in solving an initial-value problem for a parabolic PDE.

But there’s a catch. For this argument to make sense, we need the result to be independent of the details of our discrete grid. But there is one parameter $\sigma$ remaining in the final equation. Clearly the option value will depend on what value we pick for $\sigma$. We will see below that $\sigma$ is a measure of how much the stock price jumps around.

How do we know that more general formulas for our binomial tree would not give us even more different results? We have only given a plausibility argument that that does not happen: we constructed a model with two parameters and showed that one of them didn’t matter. A full answer to that question is most naturally given in terms of stochastic calculus (though there may also be PDE proofs).
3.3 Solution of the Black-Scholes equation

We will not go through in detail the manipulations by which one obtains exact solutions to Equation (3.2); for sufficiently complicated problems one can bring to bear all the tricks and techniques available for solving parabolic equations in one dimension. We will only indicate the general method of solution, and give the two most famous solutions.

The first fact to notice is that (3.2) is linear and has nonconstant coefficients. The first fact is wonderful; in fact linear equations are the rule in finance rather than the exception.

The nonconstant coefficients are easily corrected. Since $S$ appears only in the combination $S \delta S$, it is natural to change to a logarithmic variable. Introduce new independent variables

$$ x = \log \frac{S}{S_{ref}}, \quad \tau = \sigma^2 (T - t) $$

where $S_{ref}$ is any reference price, and we are reversing and rescaling time only for convenience. Look for solutions in the form

$$ V(S, t) = V_{ref} u \left( \log \frac{S}{S_{ref}}, \sigma^2 (T - t) \right) $$

where $u(x, \tau)$ is a new dependent function, and $V_{ref}$ is any convenient scale for the option value. Then (3.2) becomes

$$ u_{\tau} = \frac{1}{2} u_{xx} + \beta u_x - \gamma u, $$

in which the coefficients are

$$ \beta = \frac{r - \frac{1}{2} \sigma^2}{\sigma^2}, \quad \gamma = \frac{r}{\sigma^2}. $$

We can easily solve this equation using Green’s functions.

In particular, the most famous solutions are those for the vanilla European call and put options. For a call with strike price $K$ we have

$$ C(S, t) = SN \left( \frac{\log(S/K) + \left( r + \frac{1}{2} \sigma^2 \right) (T - t)}{\sigma \sqrt{T - t}} \right) $$

$$ - K e^{-r(T-t)} N \left( \frac{\log(S/K) + \left( r - \frac{1}{2} \sigma^2 \right) (T - t)}{\sigma \sqrt{T - t}} \right) $$
where $N(\cdot)$ is the cumulative normal distribution. The put value can be obtained by put-call parity. This formula is called the Black-Scholes formula.

Figure 3.3 shows a comparison of the “theoretical” value given by the Black-Scholes formula with the data from the Wall Street Journal for Dell call options. The traded options are actually American, whereas the explicit Black-Scholes formula applies only to European options. In general, the possibility of early exercise increases the value of the option. But for a call option on an asset that does not pay dividends (or whose dividends can be neglected), exercise before expiry is never optimal and the American value is equal to the European one.

To evaluate the formula, we need values for all the parameters. Some are unambiguously known: $S$ is the stock’s current price; $K$ is the independent variable, and $r$ is the interest rate, typically 5 or 6 percent. I adjusted the volatility $\sigma$ to get a good fit. This graph is with $\sigma = 0.6$, a rather large value since this is a volatile stock. With $\sigma = 0.6$, the size of the expected changes in the course of one year are about $\sigma^2 = 36\%$.

Alternatively, we can recognize that the price given by our made-up model is less convincing than the actual price quoted by the market. So
we take the market prices as given, and determine the volatility independently for each different strike price (and each different maturity date) so as to reproduce that market price. This number is called the \textit{implied volatility}. Figure 3.4 shows the result.

In effect, we have traded one problem for another. We know the option value in terms of the volatility, but we still need a value for the latter. Options are really ways to buy and sell volatility.

Although this data set does not show it very well, it is clear that the volatility that the market uses is larger when the spot price and the strike price are far apart. This is called the \textit{volatility smile} and is present in all options markets. It indicates that the market's assessment of the significance of large moves is greater than can be accounted for in the framework of the continuous-time limit of a binomial model.

\textbf{3.4 Dynamic hedging}

It is important to remember why there exists a formula for the price at all. The reason is that there exists a strategy of buying and selling the underlying stock and borrowing/loaning cash at a risk-free rate, that exactly duplicates the option payout. If it were impossible to carry out this strategy for some reason (for example, the exchange on which the stock is
traded closes earlier than the option exchange) then mathematical theory says nothing about the price of the option.

We discussed dynamic hedging in the discrete-time context in Chapter 1: the strategy was that you should hold $\Delta$ units of the stock, where $\Delta$ depended on what node you had reached in the evolution. As time evolved, and the price moved along its finite set of possible paths, you adjusted your holding with every change.

The exact value of $\Delta$ was given in (1.4): $\Delta = (V_2 - V_1)/(S_2 - S_1)$. On the tree, subscripts 1 and 2 refer to two children of the same node, at the same time. Therefore, in the continuum limit, this ratio approaches the first $S$-derivative of $V$ in the neighborhood of the nodes in question. Thus

$$\Delta = \frac{\partial V}{\partial S}.$$ 

As on the discrete tree, you have to solve the entire problem before you can find the initial value of $\Delta$.

As time evolves, the stock price will change as well. Unless the parameters of the problem change, the function $V(S,t)$ will remain the same. But we must continuously adjust our hedge holdings to equal the value of $\partial V/\partial S$ wherever we are on the tree at that time.

3.5 American options

All the analysis we have done so far is for European options. At each step, we have determined the arbitrage-free option value based on our holding it until the next time level.

If the option is American, then we have another possibility to consider. For each value of $S$ and $t$, there is a payoff function $\Lambda(S,t)$ that tells us how much we can get by exercising the option now. (For vanilla puts and calls, and many others, $\Lambda$ is independent of $t$.) Certainly the value of the option can never be less than $\Lambda$, since we can exercise and get that amount. What do we do if the value predicted by the binomial formula is less than the value of early exercise?

Answer: in the discrete tree computation, we replace the no-arbitrage pricing value by the value of early exercise, if the latter is larger than the former. Then keep working backwards on the tree, applying this strategy at every node; values "upstream" from the node at which you exercised will feel the effect of the increase of value due to exercise. Note that the
first level of the iteration is exactly as before, since the terminal value is exactly the exercise value.

This may seem like not a valid strategy. You may have doubts along the lines of “But if I exercise the option at some time, then for all future times it is worthless.” So shouldn’t the “downstream” nodes be set to zero? It seems like an impossible problem.

The resolution of these conceptual difficulties is to keep in mind the original meaning of a “price”. When we say that “the price at node \((i, j)\) is \(V_{i,j}\),” we literally mean that that is the market price in that circumstance. If you waited until time \(i\), and if the price at that time were \(S_j\), then if someone walked up to you and offered an option deal at price \(V_{i,j}\), you would comfortably buy or sell the option at that price. If you exercise your option, that does not affect the price at which you would buy another one.

In the continuous-time limit, the parabolic equation (3.2) becomes a parabolic variational inequality. It becomes the pair of inequalities

\[-V_t \geq \frac{1}{2} \sigma^2 V_{SS} + rSV_S - rV \quad \text{and} \quad V(S, t) \geq \Lambda(S, t)\]

combined with the condition that at each point \((S, t)\), either \(V = \Lambda\), or the Black-Scholes equation is satisfied (with equality). This condition arises from the requirement that \(V(S, t)\) must be the smallest value that satisfies both of the inequality constraints.

As a consequence of these conditions, the \((S, t)\)-plane is divided into two regions: the “exercise region,” in which the most optimal strategy is to exercise the option, so \(V(S, t) = \Lambda(S, t)\), and the “free region,” in which it is better to hold the option, so that Eq. (3.2) holds. The curve dividing one region from the other is called the exercise boundary, which tells you when you should exercise in terms of the underlying price.

The presence of the free boundary transforms what was a simple linear PDE with explicit solutions into a horrible nonlinear problem. This free boundary problem is equivalent to the one-dimensional Stefan problem, and some techniques from that problem can be applied. In addition, there is a rich variety of asymptotic and approximate solution methods.

One saving grace, which we invoked above, is that early exercise is never optimal for a call on an asset that does not yield dividends. The reason is that you will wind up with the same asset at time \(T\) whether you exercise now or at the last minute, and by exercising at the last moment you can continue to earn interest on the money you are saving to pay the exercise price.
Chapter 4

Stochastic Models

The time has come to be a little more explicit about exactly what we mean by these binomial trees. We have seen that the nature of the model we construct, in particular the value of \( \sigma \) associated with the branches on our trees, has an important effect on the final computed value of the option. So we need some idea what feature of the real world this corresponds to.

Now, for the first time, let us introduce probabilities and expected motions. Suppose that our belief about the future motion of the asset price is that it will move on the binomial grid we have laid down. Suppose now that we imagine that at each juncture, it has probability \( p \) to take the upwards branch, probability \( 1 - p \) to move downwards. We didn't need the value of \( p \) to determine our option values—we were completely covered no matter which way it went—but we need it to give a “physical” description of what is happening.

Under this model, the price executes a random walk. Its probability distribution at any time can readily be computed. In the continuum limit, on our tree with proportional increments, this distribution is a lognormal distribution, meaning that its logarithm is normally distributed (a Gaussian). Financial models were one of the first areas of application of random walks; Bachelier (1900) proposed the Gaussian distribution for asset price movements.

The expected value of the price under this distribution is controlled by the probability \( p \), and by the “drift” of the tree, \( s \). We know that neither of these parameters matters for the option value.

But the variance of the distribution is, to a large extent, independent of the drift terms (as long as the total growth is not too large). In the
continuum limit, this variance approaches a finite value which is precisely
our parameter $\lambda$ or $\sigma$ (this convergence requires that $p \to \frac{1}{2}$ as $h, k \to 0$;
if $p$ does not go to $\frac{1}{2}$ then the stock motion is unboundedly rapid in the
limit).

The motion of the asset price $S(t)$ then acquires a probabilistic in-
terpretation. It may be written as a stochastic differential equation which
for the simplest case of lognormal distribution has the form

$$dS = \mu S dt + \sigma S dX,$$

where $dX$ is the infinitesimal increment of a pure Brownian motion. The
coefficient $\mu$ is an expected drift term which eventually disappears from
the model via a change of measure. The option pricing model is con-
structed with the same philosophy as on the binomial tree: a hedging
portfolio is constructed that (by use of Ito’s lemma) must grow at a risk-
free rate.

The description based on stochastic calculus is more general: for ex-
ample, $\sigma$ can depend on $S$ and $t$. This is one way to describe the volatility
smile; it is equivalent to writing $\sigma(S, t)$ in the Black-Scholes PDE (3.2).
Stochastic differential equations with more general forms are essential
for modeling interest rate products.

The mathematics of stochastic analysis is so elegant that it tends
to lend an air of inevitability to its conclusions. Indeed, the Central
Limit Theorem says that whenever a process grows by accumulating suf-
ciently many uncorrelated small increments, its statistics must be lo-
cally Gaussian. But there is plenty of evidence from financial markets
that statistics are not Gaussian (the volatility smile, for example), so one
must always be on one’s guard.
Sources and further reading

The classic no-arbitrage theory of Chapter 1 is the first chapter or two of Dothan, Duffie, and Pliska, and most of the rest of this material can be found there as well. The binomial model for stock price motion, and option pricing on a binomial tree, is straight out of Cox & Rubinstein. Baxter & Rennie and Neftci are also good introductions to the basic theory. Chriss has a great deal of detail on various advanced binomial trees, such as implied volatility trees. Wilmott is an introduction to everything. Taleb gives a highly entertaining account of how these models are used in practice.

For a good general introduction to the various kinds of derivative securities and markets, see Hull. For background information on the economic fundamentals of markets, see Houthakker and Williamson. Malkiel gives a popular treatment of the efficient market theory.

Wilmott, Howison, & Dewynne is a good introduction to PDE methods in derivative pricing. The convergence theory for finite-difference approximations can be found in any basic book, such as Smith or Morton & Mayers. Kwok has wide coverage of PDE, Monte Carlo, and other methods, for options and for interest rates. For an overview of recent research activity, see the conference proceedings volumes by Dempster & Pliska and Rogers & Talay.

We have only touched on the use of stochastic processes to model financial derivatives (because of its technical difficulty). But that is a huge, important and fruitful area of modeling. Øksendal is a good introduction. For readers who are already familiar with stochastic analysis, Karatzas & Shreve, and Lamberton & Lapeyre give a good overview of the applications to finance.

There is growing appreciation of the importance of non-Gaussian distributions in financial markets, and practical pricing methods are beginning to be developed. Mandelbrot collects some of his seminal work in the field; Bouchaud and Potters give an excellent modern account of the data, theories and models.

• Darrell Duffie, Dynamic Asset Pricing Theory, Princeton 1996 (2nd ed.).
• Benoit B. Mandelbrot, Fractals and Scaling in Finance: Discontinuity, Concentration, Risk, Springer 1997.
• Stanley R. Pliska, Introduction to Mathematical Finance: Discrete Time Models, Blackwell 1998 (2nd ed.).